## Short Manual ST@Drive for ST500 series

Important! Work on the drive only when switched off! Measure the voltage before work to make sure there is no danger. All work must be done by electrical professionals.

1. Connect the brown wire to the clamp labeled **485**- and the (depending on the revision of the adapter) blue or white wire to the clamp labeled **485**+ as shown in picture 1 below.



## Picture 1

- 2. Connect the USB adapter to a free USB port on your computer. Windows should find and install a driver on its own when connected to the internet. Otherwise, there's a driver provided on the install CD.
- 3. Turn on the ST500 series AC drive.
- 4. Use the ST@Drive installer on the CD to install the software on your Windows PC.
- 5. Start the ST@Drive software.

6. Open the dialog to add a new device by clicking the green menu button and then the "Add device manually" button as shown in picture 2:

Sourcetronic ST® Drive				– 🗆 X
File Edit Communication Help				
File Edit Communication Help	- 2.			
	Address Current Device: -	Serial Port Status: -	COM-Port: -	Baud-Rate: -

## Picture 2

7. Use the popup dialog to define the correct COM Port, then click the "Add" button as seen in picture 3. The settings for device address and baud rate are the inverter's default communication settings, so unless you changed those, you can skip them here.

Sourcetronic ST®Drive				- 🗆 ×
File Edit Communication Help				
	Add a new device	×		
	Device address	1		
	COM-Port	COM1 -		
	Baud-Rate	9600 -		
	display as			
	Add	Don't Add		
	+			
	Address Current Device: -	Serial Port Status: -	COM-Port: -	Baud-Rate: -

Picture 3

## 8. If the device is not found even though it is connected and switched on, try another COM

port.

9. Expand the device tree on the left side, then you can select the parameter groups and view and change individual parameters.

Device #1 (addr. 1)		EO Pasia	function			
<ul> <li>All Parameter Groups</li> </ul>	FU - Basic function group					
F0 Basic function group	Register	Description	Device Value	Range	Unit	Default Value
F1 Input terminals group	F0 00	Motor control manner		0 - 2		
F2 Output terminals group	F0 01	Keyboard set frequency		0.0 - 50.0	Hz	50
F3 Start and stop control group	F0 02	Frequency command resolution		1 - 2		
F4 V/F control parameters	F0 03	Frequency source master setting		0 - 9		
F5 Vector control parameters	F0 04	Frequency source auxiliary setting		0 - 9		
F6 Keyboard and display	F0 05	Reference object selection for frequency source auxiliary s		0 - 2		
F7 Auxiliary function group	F0 06	Frequency source auxiliary setting range		0 - 150	%	1
F8 Fault and protection	F0 07	Frequency source superimposed selection		0 - 3		
F9 Communication parameter	F0 08	Frequency source offset frequency when superimposing		0.0 - 50.0	Hz	
FA Torque control parameters	F0 09	Shutdown memory selection for digital set frequency		0 - 1		
FB Control optimization parameters	F0 10	Frequency command UP / DOWN reference when running		0 - 1		
FC Extended paremeter group	F0 11	Command source selection		0 - 4		
E0 Wobbulate, fixed-length and countin	F0 12	Binding frequency source for command source		0 - 999		
E1 Multi-stage command, simple PLC	F0 13	Acceleration time 1		0.0 - 650.0	c	
E2 PID function	F0 14	Deceleration time 1		0.0 = 650.0		
E3 Virtual DI, Virtual DO	F0 15			0 - 2	-	
bu motor parameters	F0 16			0.2		
V1 Fould even	50.17	Carrier frequency adjustment as per temperature		0-1		
Chaption	E0 19	Carrier Frequency		05-160	6U~	
Overview	50.10	Maximum autorit formum		50.0 220.0	KI IZ	5/
	F0 19	Maximum output irequency		50.0 - 520.0	nz.	JC
	F0 20	Upper limit frequency source		0-0		
	FU 21	Upper limit frequency		0.0 - 50.0	Hz	50
	F0 22	Upper limit frequency offset		0.0 - 50.0	Hz	

Picture 4